

Кратчайшие пути, часть 1

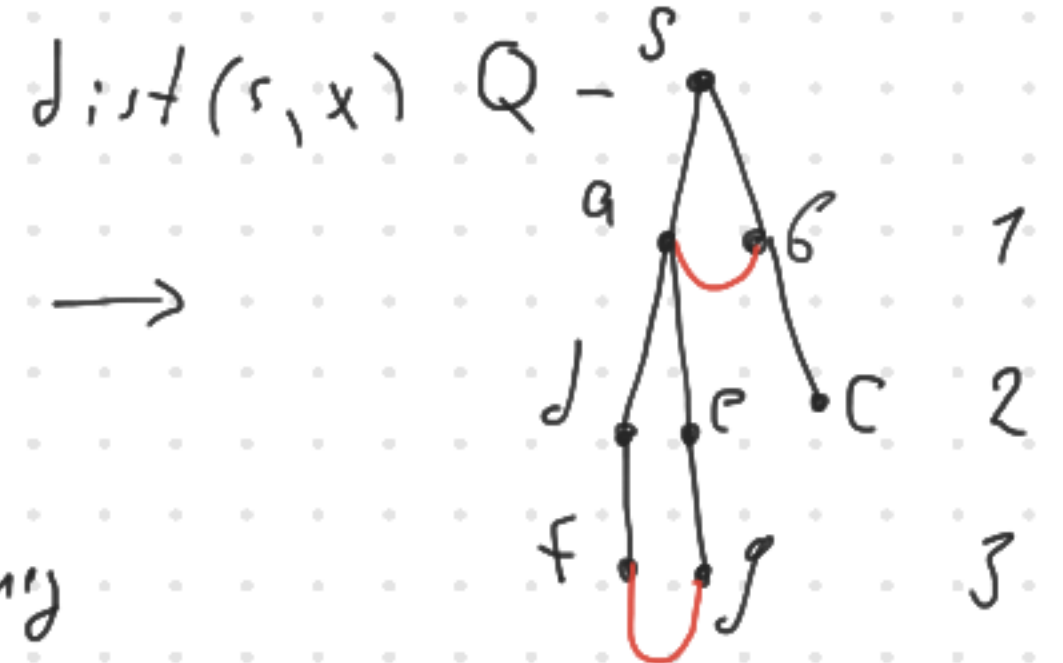
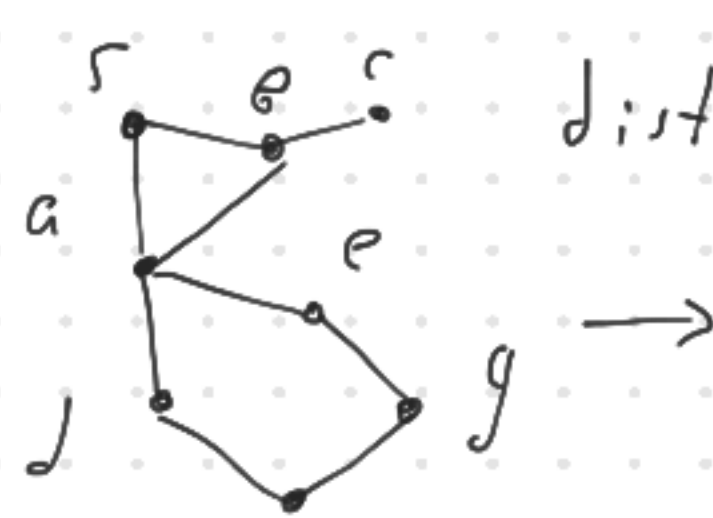
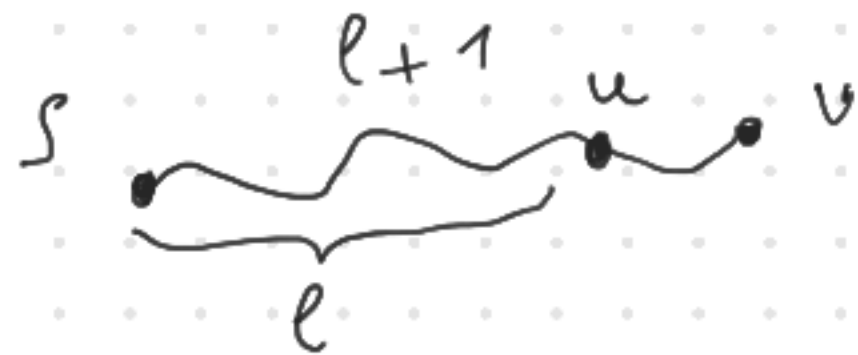
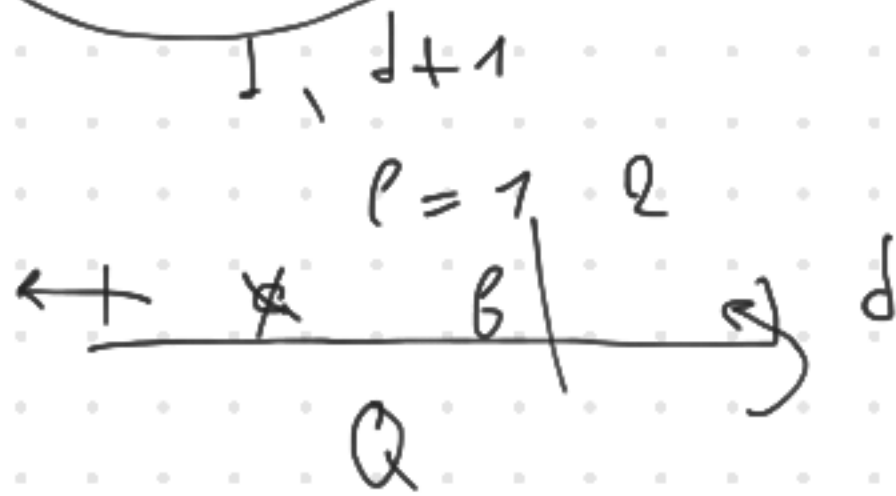
DFS стек / функция

время входа / выхода
previsit / postvisit
connected comp.



$dist(u, v)$ - # ребер
в кр. пути $u \rightarrow v$

$d \rightarrow d+1$



0	Q	*
1		* b
2		* d e
3		d e c
4		e c f
5		c f g
6		f g

Упр BFS
(breadth-first search)
короткий - т.е.
все facets. Белая
Queue для всех белых
 $c \text{ facets} \leq l \text{ бел. кott.}$
① $\rightarrow l+1$

Figure 4.3 Breadth-first search.

procedure `bfs`(G, s)

Input: Graph $G = (V, E)$, directed or undirected; vertex $s \in V$

Output: For all vertices u reachable from s , $\text{dist}(u)$ is set to the distance from s to u .

for all $u \in V$:

$\text{dist}(u) = \infty$

$\text{dist}(s) = 0$

$Q = [s]$ (queue containing just s)

while Q is not empty:

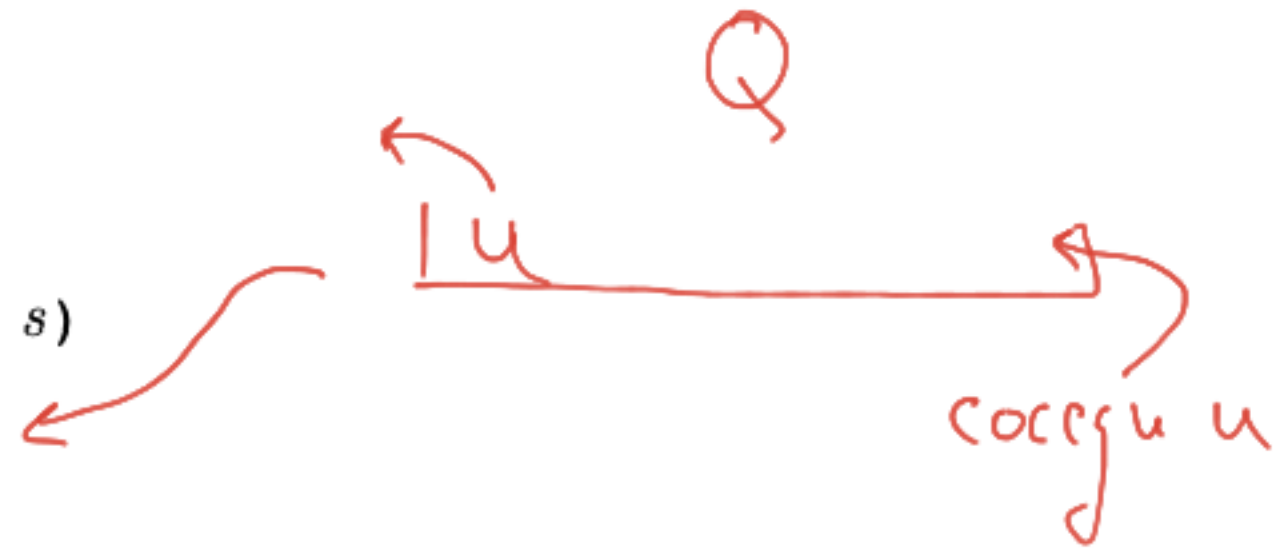
$u = \text{eject}(Q)$

for all edges $(u, v) \in E$:

if $\text{dist}(v) = \infty$:

inject(Q, v)

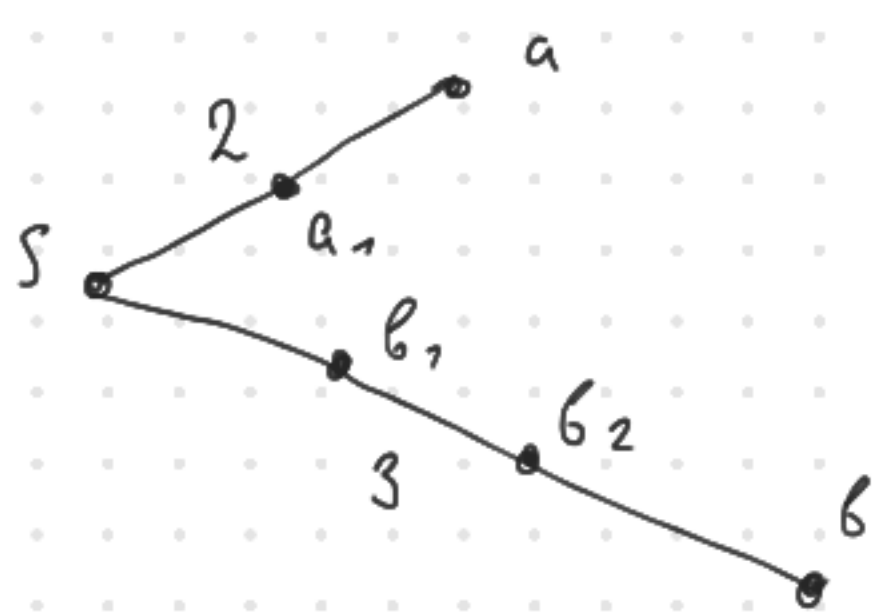
$\text{dist}(v) = \text{dist}(u) + 1$



$O(n + m)$



•



$$l: E \rightarrow \mathbb{N}$$

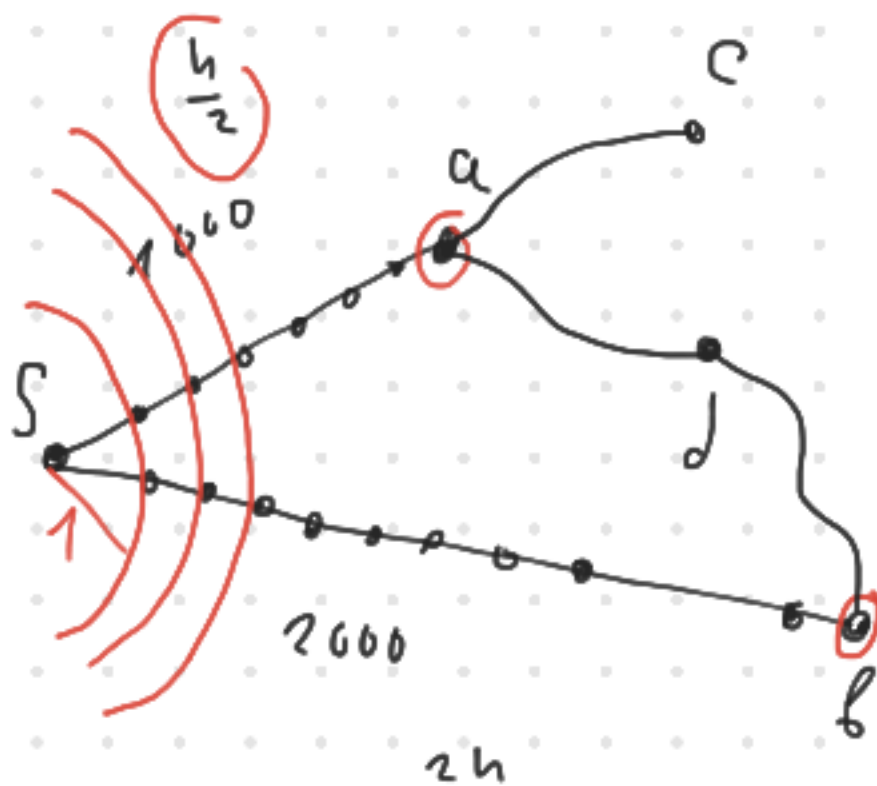
$l(e)$ — длина

$$l(e) \leq k - \text{const}$$

$$O(n + m)$$



"Намму s в t=0"



содитна "Намму берем x"

"Намму s в момент t=0"

"Намму a в момент l_{sa} "

"Намму b в момент l_{sb} "

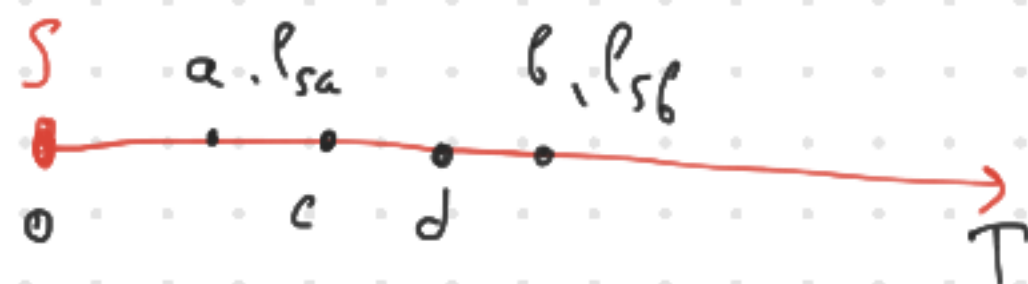
1) загата $\text{dist}(s) = 0$
 $\text{dist}(x \neq s) = \infty$

2) пока есть события:

(u, t) — диме. сод.
где $v \in \text{соседи } u$:

если v не бер.
годаб (v, ∞)

если v бер.
обновит
касст.



$$\text{dist}(s, a) + l_{ac} < l_{sb}$$

\Rightarrow c faster to b

priority queue
delete_min()
insert(v, t)
decrease_key(v, t)
 (v, ∞)

Figure 4.8 Dijkstra's shortest-path algorithm.

procedure `dijkstra(G, l, s)`

Input: Graph $G = (V, E)$, directed or undirected;
positive edge lengths $\{l_e : e \in E\}$; vertex $s \in V$

Output: For all vertices u reachable from s , $\text{dist}(u)$ is set to the distance from s to u .

for all $u \in V$:
 $\text{dist}(u) = \infty$
 $\text{prev}(u) = \text{nil}$
 $\text{dist}(s) = 0$

$H = \text{makequeue}(V)$ (using dist -values as keys)

while H is not empty:

$u = \text{deletemin}(H)$

for all edges $(u, v) \in E$:

if $\text{dist}(v) > \text{dist}(u) + l(u, v)$:

$\text{dist}(v) = \text{dist}(u) + l(u, v)$

$\text{prev}(v) = u$

$\text{decreasekey}(H, v)$



BFS

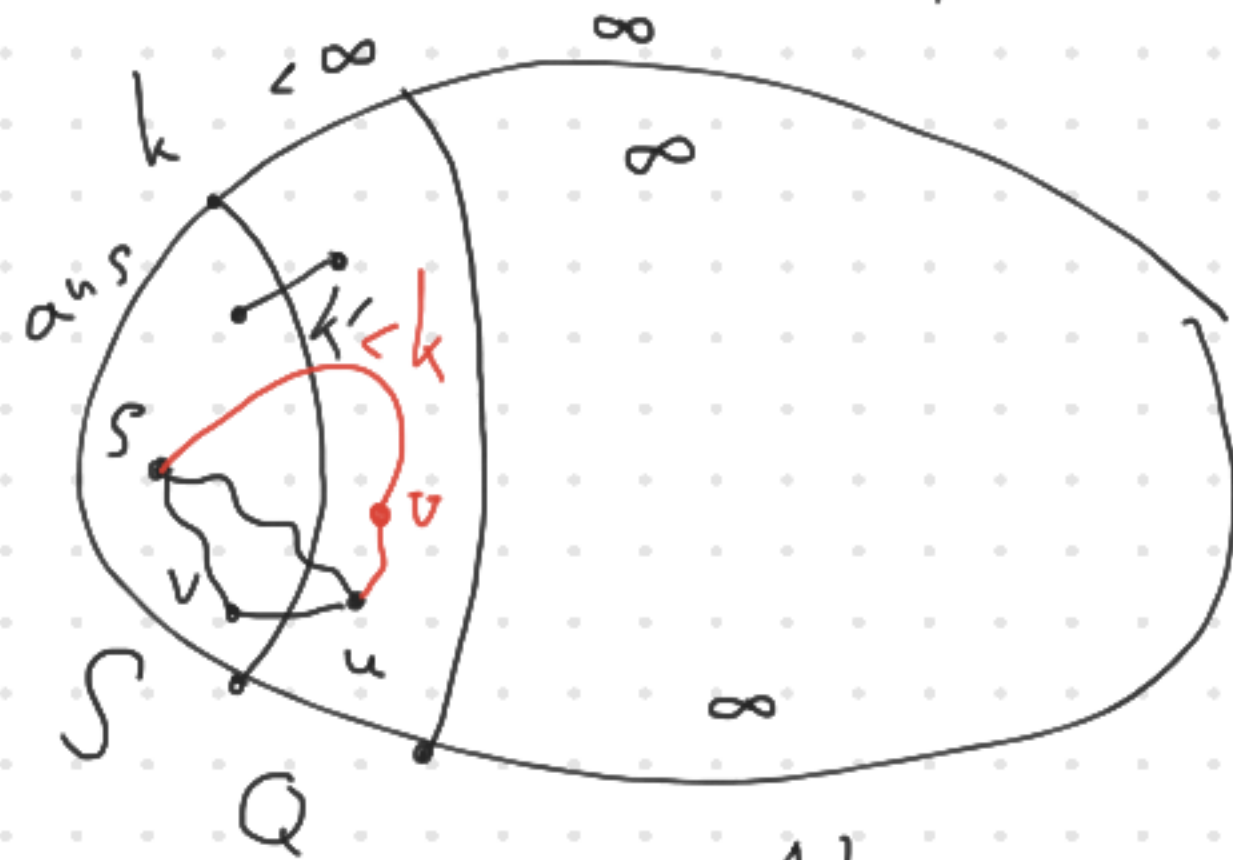


$$l_{uv} \in \mathbb{R}_{\geq 0}$$



УТБ алг. Дейкстры
корректен

k - известная область
 $k=0$
 граница области
 в обработке



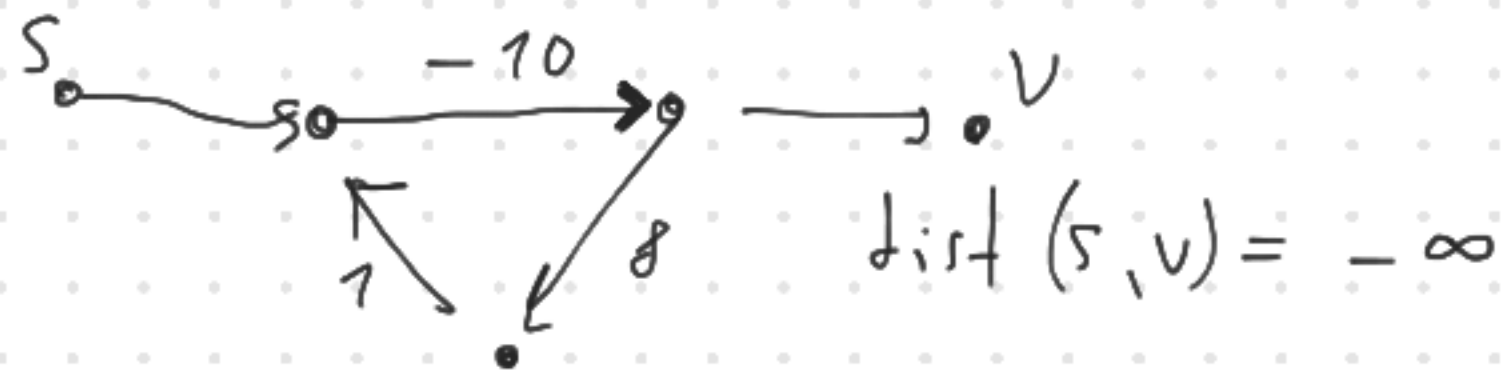
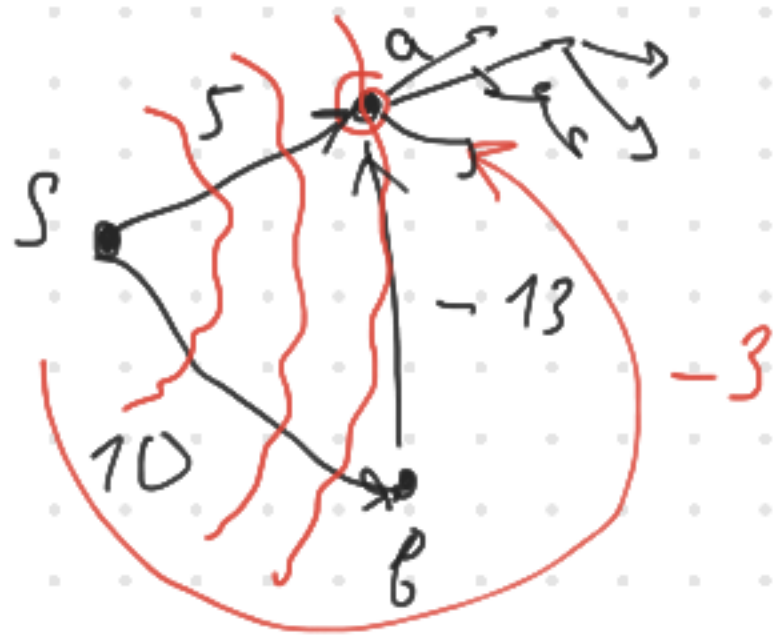
Итак мы и фиксируем $\text{dist}(s, u)$

$V = \left(\begin{array}{l} S = \{ \text{уже обработанные узлы пр. q. вершины} \} \\ Q = \{ \text{верш. в пр. q.} \} \\ N = \{ \text{верш., кот не были в пр. q.} \} \end{array} \right.$

Пояснение

пусть $u \in Q$ $\text{dist}(s, u) = k$
 для всех $k' < k$ верно

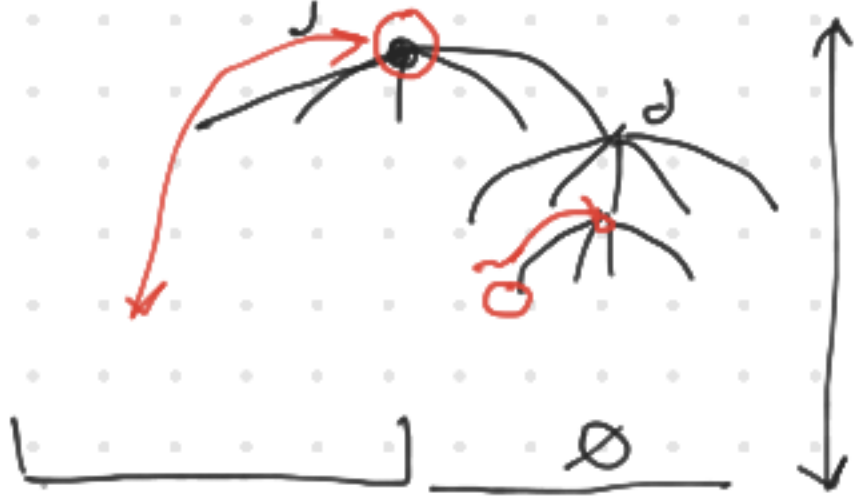
1) $v \notin S$ $\text{dist}(s, v) \geq k$
 2) $v \in S \Rightarrow \text{dist}(s, v) < k$ (?)



0-k BFS

Implementation	deletemin	insert/ decreasekey	$ V \times \text{deletemin} + (V + E) \times \text{insert}$
Array	$O(V)$	$O(1)$	$O(V ^2)$
Binary heap	$O(\log V)$	$O(\log V)$	$O((V + E) \log V)$
d -ary heap	$O(\frac{d \log V }{\log d})$	$O(\frac{\log V }{\log d})$	$O((V \cdot d + E) \frac{\log V }{\log d})$
Fibonacci heap	$O(\log V)$	$O(1)$ (amortized)	$O(V \log V + E)$

min



$$\frac{E \log |V|}{\sqrt{|V|}}$$

$$\log_d h = \frac{\log_2 h}{\log_2 d}$$

$$\log_2 h \cdot \log_2 d = \log_2 h = h$$